

Sparsest Cut Problem in Graphs and its Parallel Algorithms

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Abstract

In this project we are studying the sparsest cut problem in graphs and its application. We study:

- Formulation of the problem and its various generalization.
- Spectral algorithms and their applications in data clustering
- An efficient algorithms on weighted trees
- An implementation of the above algorithm in parallel using CUDA platform
- Experimental results on various data sets

Introduction

- The *edge expansion* ("sparsity" or "Cheeger constant") of a graph G is:

$$\phi(G) := \frac{E(S, \bar{S})}{\min(|S|, |\bar{S}|)}$$

The **Sparsest Cut** problem asks to find a cut $E(S, \bar{S})$ with smallest possible sparsity.

- For a subset of vertices A in a graph G , the normalized flow of A is:

$$\frac{E(S, \bar{S})}{|S|}$$

The mean version of the problem seeks for a cut which minimize the average normalized flows of the sets S and \bar{S} .

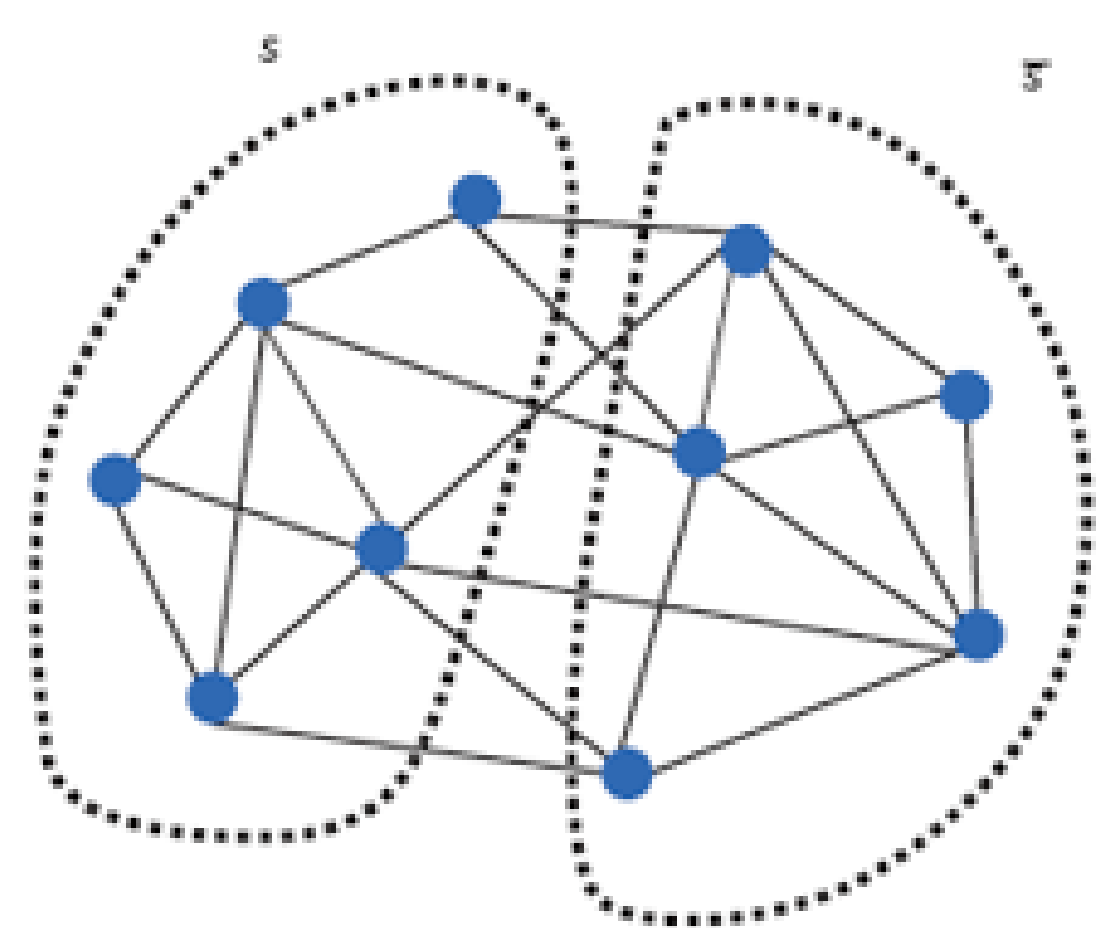


Figure 1: Sparsest Cut Solution

Problem Generalization

- k -Normalized Cut Problem:** Given a weighted graph $G = (V, E, \varphi, \omega)$ and an integer k . Find a k -partition of vertices G such that the sum (maximum) of their normalized flows is minimized.

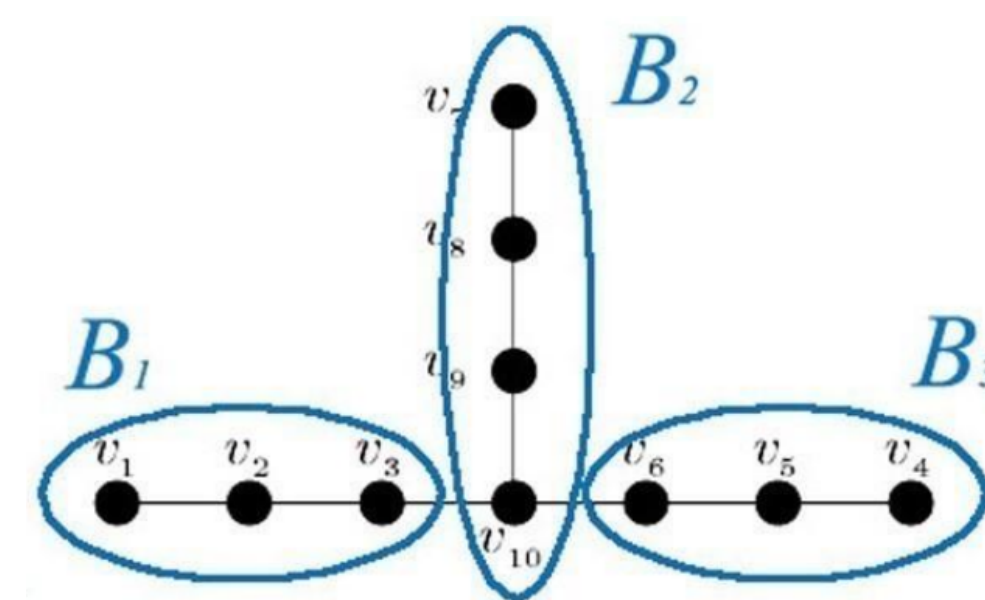


Figure 2: 3-Normalized Cut Solution

- k -Isoperimetric Problem:** The isoperimetric problem aims to minimize the normalized cut objective function over the space of subpartitions.

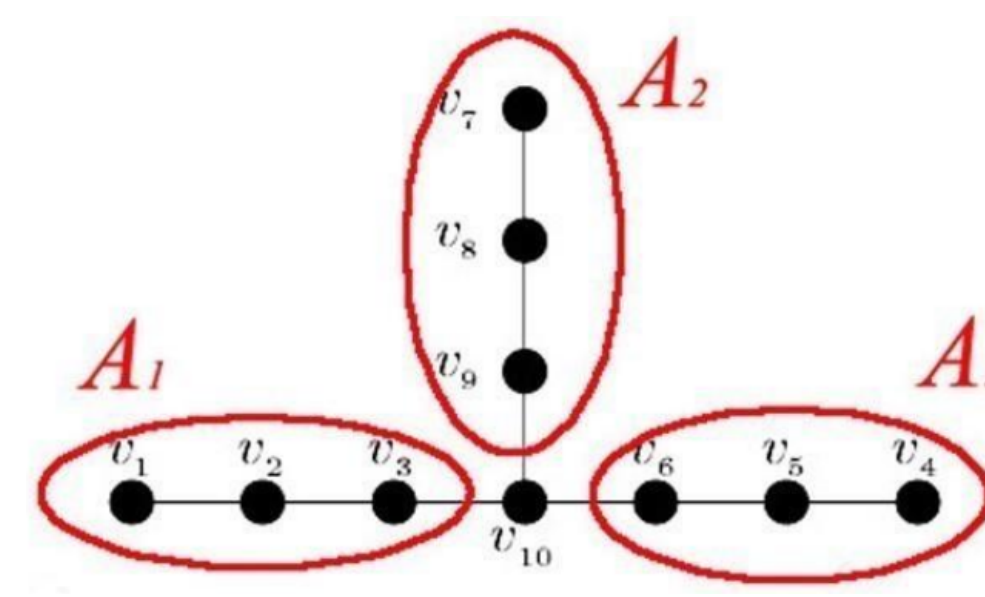


Figure 3: 3-Isoperimetric Solution

Relation to Laplacian Spectrum

Let $0 = \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_{|V|}$ be the Laplacian eigenvalues of a graph G .

- Cheeger's inequality** offers the following quantitative connection between $\phi(G)$ and λ_2 :

$$\frac{\lambda_2}{2} \leq \phi(G) \leq \sqrt{2\lambda_2}$$

- In [2], Lee et al. show the following relation for k -normalized cut problem:

$$\frac{\lambda_k}{2} \leq \phi^k(G) \leq O(k^2)\sqrt{\lambda_k}$$

- In [4], Shi and Malik, use the second Laplacian eigenvector to approximate the mean normalized cut problem.

Spectral Algorithm

- In [3], Ng et al. proposed the following approximation algorithm for k -Normalized cut problem:
 - Compute the first k eigenvectors u_1, \dots, u_k of Laplacian matrix.
 - Let $U \in R^{n \times k}$ be the matrix containing the vectors u_1, \dots, u_k as columns.
 - For $i = 1, \dots, n$, let $y_i \in R^k$ be the vector corresponding to the i -th row of U .
 - Cluster the points $(y_i)_{i=1, \dots, n}$ in R^k with the k -means algorithm into clusters C_1, \dots, C_k .

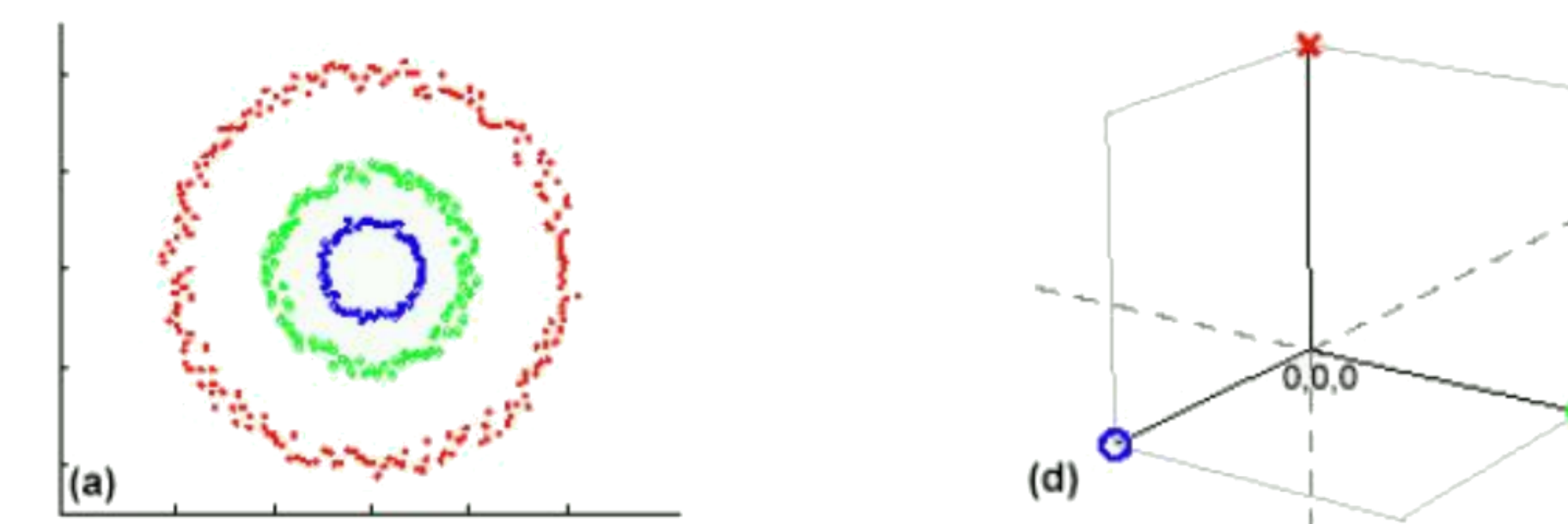


Figure 4: Spectral Projection of Data in the Algorithm

- The approximation factor of this algorithm can be bounded by higher order Cheeger's inequalities.
- The algorithm can be used as an alternative algorithm for data clustering tasks.

Algorithms on Trees

In [1], Daneshgar et al. show that the maximum k -Isoperimetric problem for weighted trees can be solved and an affirmative subpartition can be found (if exists) in time $O(n \log n)$ and proposed a clustering algorithm as follows:

- Construct similarity graph G ,
- Compute minimum spanning tree of G ,
- Solve the k -Isoperimetric problem using the algorithm in [1].

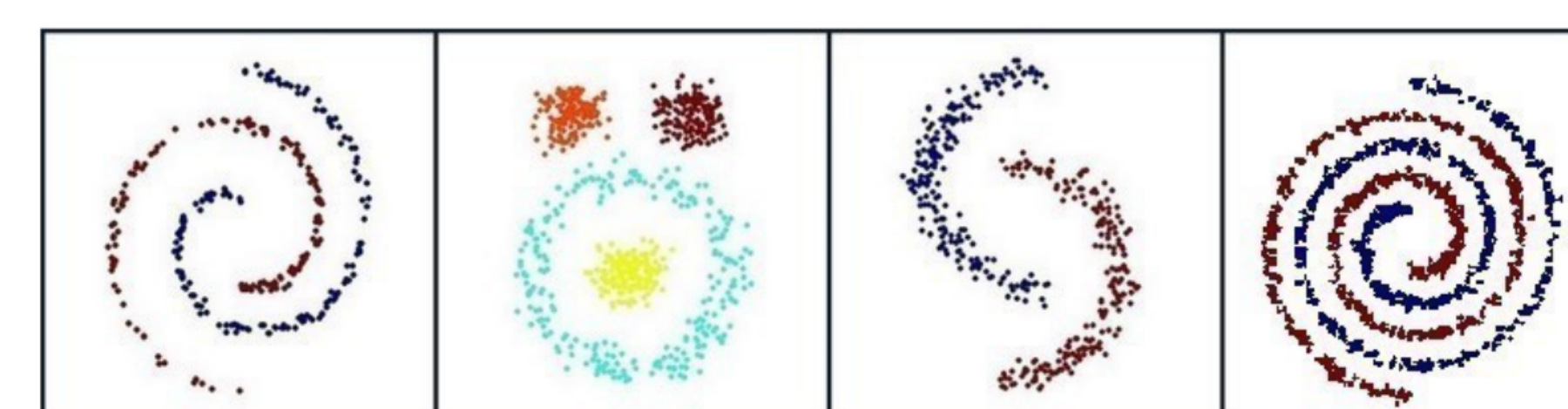


Figure 5: Experimental Results of Algorithm [1]

Parallel Implementation and Experimental Results

- We implement the first two steps of the above algorithm in parallel,
- The implementation is done using CUDA platform on Nvidia Geforce GTX 850M card.
- The sketch of the algorithm is:
 - Find all matrix elements independently in parallel,
 - Find the minimum spanning tree in parallel using algorithm in [5],
 - Solve the k -Isoperimetric problem using algorithm in [1].

Data Set	n	k	d	CPU(ms)	GPU (ms)	Speed-Up	Misclassification rate
Wine	178	3	13	12.51	58.40	0.21	0.281
Skin	2000	2	3	373	350	1.06	0.014
Yeast	1484	10	8	323	300	1.07	0.686
Wine Quality	4898	10	11	4161	956	4.35	0.844
Internet Ads	3279	2	1558	177291	9412	18.83	0.482

Figure 6: Experimental Results

References

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